

Office Hours

1-3 PM Tues.

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Shifted Systems

Monday, 6 PM

Review Sessions

S.S.

$\vec{\gamma}$  = vector

$$1) \dot{x} = A(x - \vec{\gamma})$$

$$x = C_1 e^{\lambda_1 t} v_1 + C_2 e^{\lambda_2 t} v_2 + \vec{\gamma}$$

$$2) \dot{x} = Ax + b$$

$$x = C_1 e^{\lambda_1 t} v_1 + C_2 e^{\lambda_2 t} v_2 + r$$

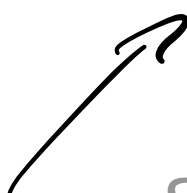
$$\text{s.t. } Ar + b = 0$$

$e^{x_1}$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$



$$x' = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 - 3 \\ x_2 + 1 \end{bmatrix}$$



$$\begin{bmatrix} 2-\lambda & 1 \\ 1 & 2-\lambda \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - v$$

$$\lambda^2 - 4\lambda + 3$$

$$(\lambda - 3)(\lambda - 1)$$

$$\lambda_1 = 1 \quad \lambda_2 = 3$$

$$\lambda_1 = 1:$$

$$\begin{bmatrix} 2-1 & 1 \\ 1 & 2-1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{matrix} \gamma_1 \\ \gamma_2 \end{matrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\gamma_1 + \gamma_2 = 0$$

$$\lambda_1 = -\lambda_2$$

$$\begin{bmatrix} -\lambda_2 \\ \lambda_2 \end{bmatrix}$$

$$v_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = 1$$

$$\lambda_2 = 3$$

$$= \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-1\lambda_1 + 1\lambda_2 = 0$$

$$\lambda_1 = \lambda_2$$

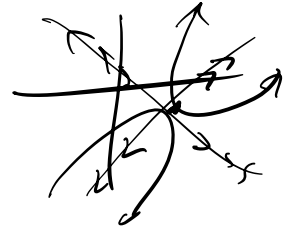
$$v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} \lambda_2 \\ \lambda_2 \end{bmatrix}$$

$$\lambda_2 = 1$$

L I I

G.S. of shifted,



$$y = C_1 e^t \begin{bmatrix} -1 \\ 1 \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

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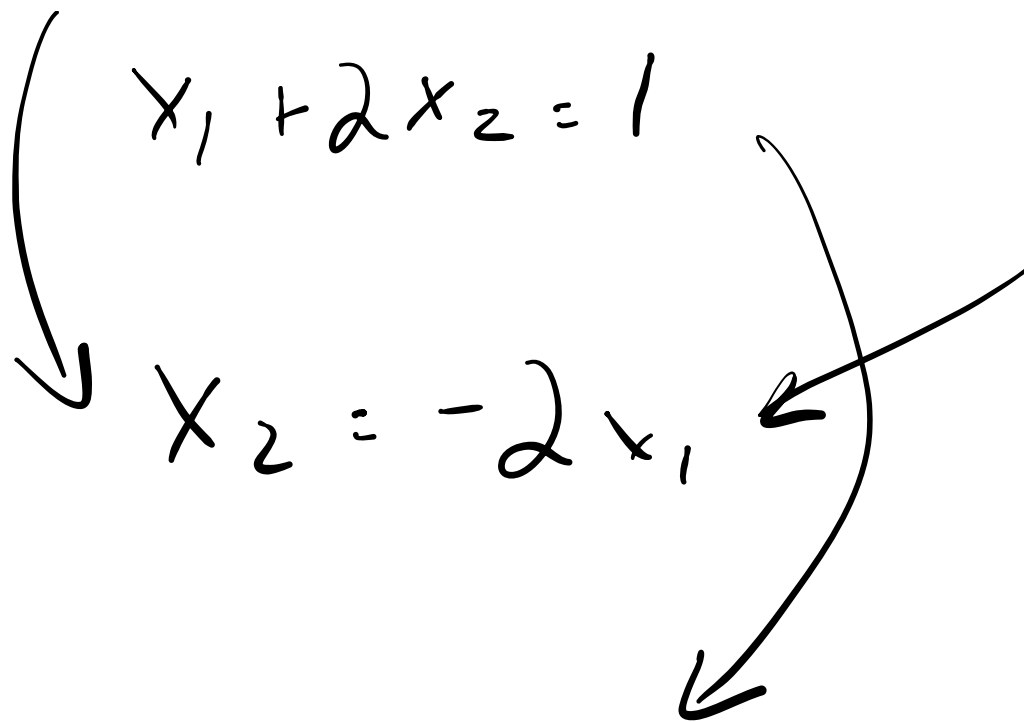
Ex 2.  $x' = Ax + b$

$$x' = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

Set 0

$$\begin{bmatrix} 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$2x_1 + x_2 = 0$$

$$x_1 + 2x_2 = 1$$
$$x_2 = -2x_1$$


$$x_1 + 2(-2x_1) = 1$$

$$x_1 - 4x_1 = 1$$

$$-3x_1 = 1$$

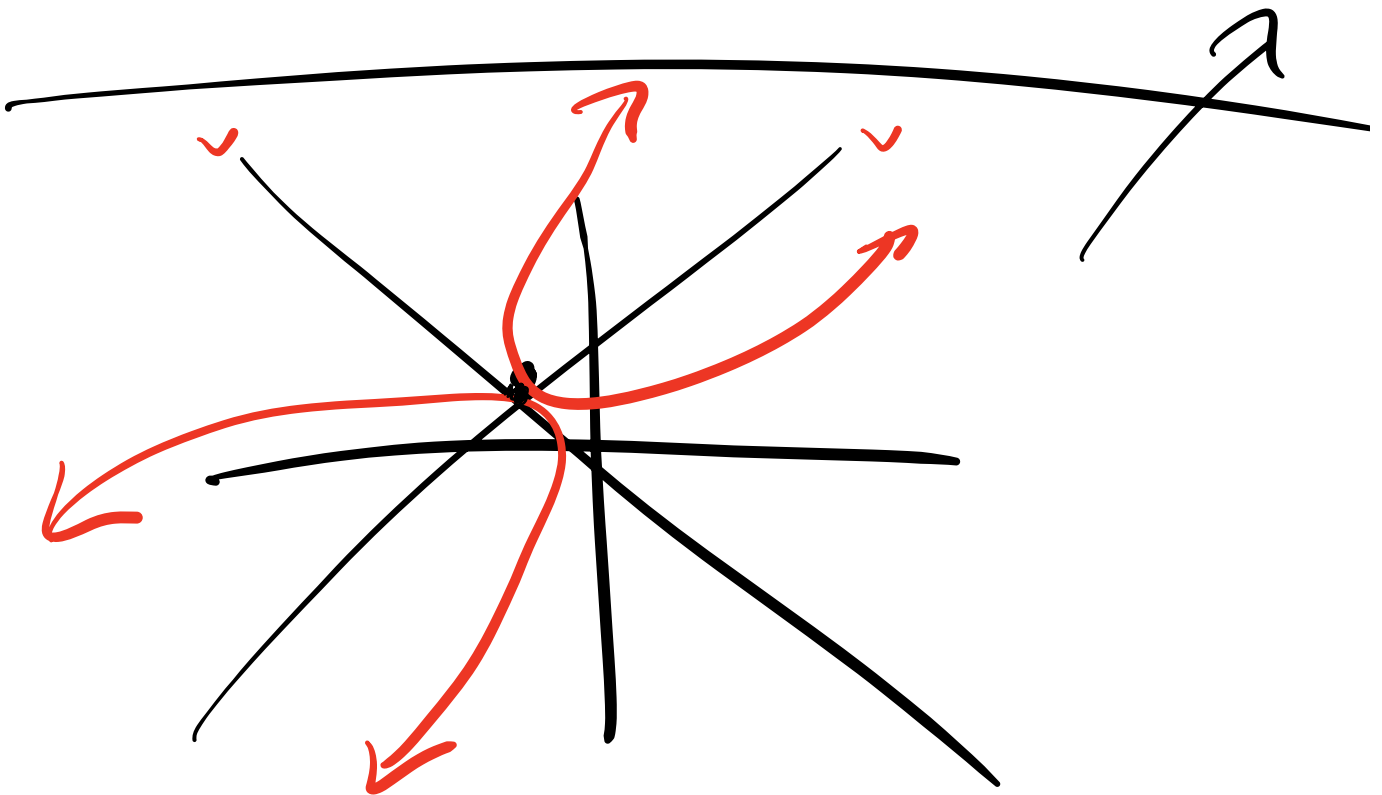
$$x_1 = -\frac{1}{3}$$

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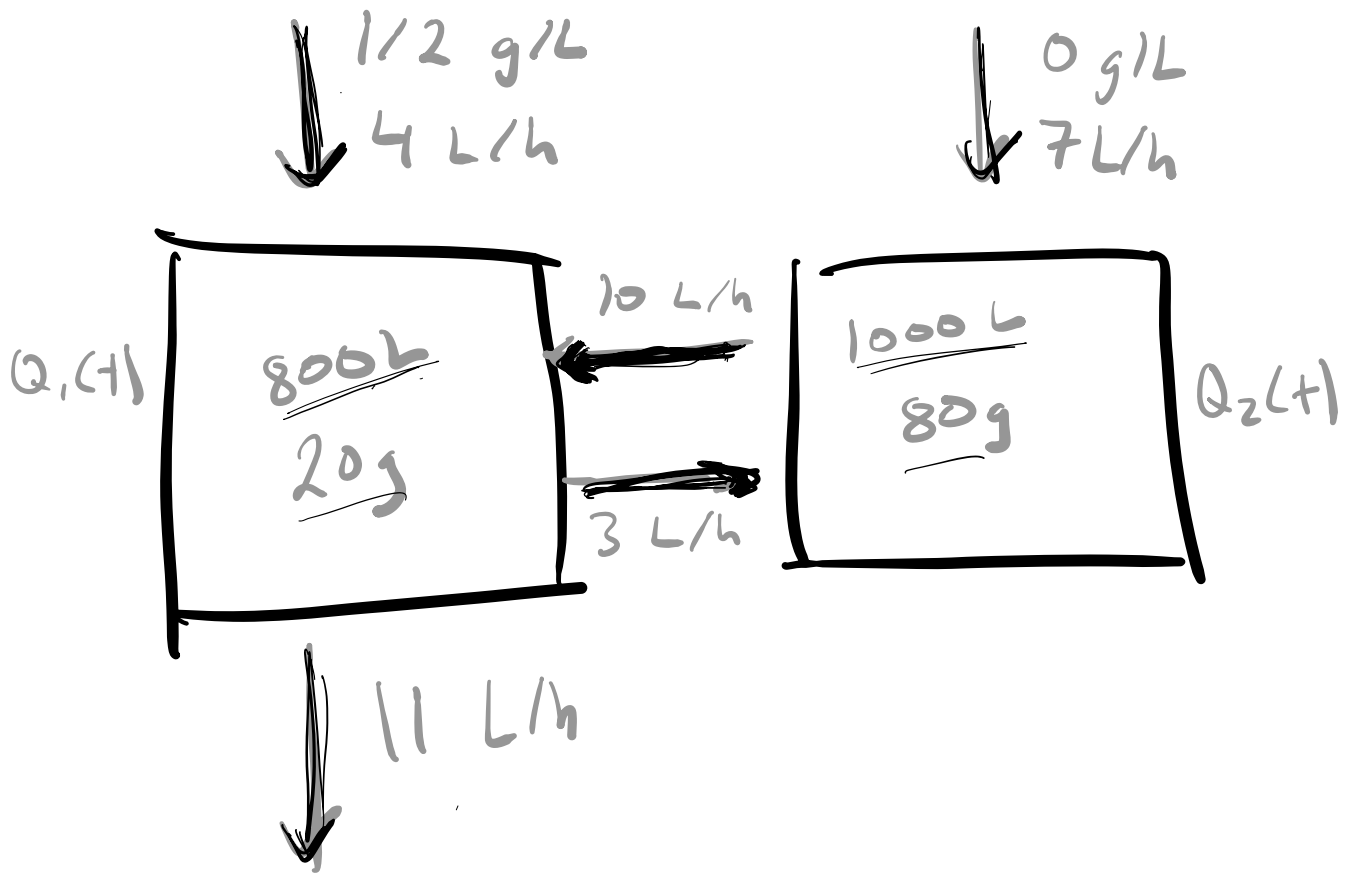
$$X_2 = \frac{2}{3}$$

y:

$$C_1 e^{t} \begin{pmatrix} -1 \\ 1 \end{pmatrix} + C_2 e^{3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{bmatrix} -1/3 \\ 2/3 \end{bmatrix}$$



2 Salt Tanks



$$\frac{dQ}{dt} = C_i(t) r_i(t) - \left\{ \frac{Q(t)}{V(t)} \right\} r_o(t)$$

$i_n$   $\nearrow$

$\nearrow$   $out$



- 1) Salt entering externally
- 2) salt entering from other tank
- 3) salt leaving

$$\begin{array}{r}
 1 \quad + \quad 2 \quad - \quad 3 \\
 cr \quad \quad cr \quad \quad \quad cr
 \end{array}$$


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$Q_1 :$

$$\begin{array}{l}
 \left. \begin{array}{l} 1) \\ 2) \end{array} \right\} \begin{array}{l} 4 \left( \frac{1}{2} \right) \\ 10 \left( \frac{Q_2}{1000 + 10t - 10t} \right) \end{array}
 \end{array}$$

$$\text{out } (3) \quad 14 \left( \frac{Q_1}{800 + 14t - 14t} \right)$$

$$\frac{dQ_1}{dt} = 1 + 2 - 3$$

$$= 4 \left( \frac{1}{2} \right) + 10 \left( \frac{Q_2}{1000} \right) - 14 \left( \frac{Q_1}{800} \right)$$

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$$\frac{dQ_1}{dt} = 2 + \frac{Q_2}{100} - \frac{7Q_1}{400}$$

$$Q_1(0) = 20$$

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$$\frac{dQ_2}{dt} =$$

- 1) Salt entering externally
- 2) salt entering from other tank
- 3) salt leaving

1) 0

2)  $3 \left( \frac{Q_1}{800 + 14t - 14t} \right)$

3)  $10 \left( \frac{Q_2}{\quad} \right)$

$$\sqrt{1000 + 10t - 10t} \quad |$$

$$\frac{dQ_2}{dt} = 1 + 2 - 3$$

$$= \frac{3Q_1}{800} - \frac{Q_2}{100}$$

$$Q_2(0) = 80$$

$$\frac{dQ_1}{dt} = 2 + \frac{Q_2}{100} - \frac{7Q_1}{400}$$

$$\frac{dQ_2}{dt} = \frac{3Q_1}{800} - \frac{Q_2}{100}$$

$$Q_1(0) = 20$$

$$Q_2(0) = 80$$

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$$Q' = \begin{bmatrix} -\frac{7}{400} & \frac{1}{100} \\ \frac{3}{800} & -\frac{1}{100} \end{bmatrix} \begin{bmatrix} Q_1 \\ Q_2 \end{bmatrix} + \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$Q(0) = \begin{bmatrix} 20 \\ 80 \end{bmatrix}$$