

1 -

There will be one problem on solving a system of 1st order linear ODE's.
For example,

$$\frac{dx_1}{dt} = 1x_1(t) + 2x_2(t)$$

$$\frac{dx_2}{dt} = 4x_1(t) + 3x_2(t)$$

1) Find eigenvalues

2) Find eigenvectors

3) Find General Solution

4) Plot phase portrait

Solution.

1) Find eigenvalues:

$$\begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1-\lambda & 2 \\ 4 & 3-\lambda \end{bmatrix}$$

$$\Rightarrow (1-\lambda)(3-\lambda) - (8)$$

$$3 - 3\lambda - \lambda + \lambda^2 - 8$$

$$\lambda^2 - 4\lambda - 5$$

$$(\lambda + 1)(\lambda - 5)$$

$$\lambda_1 = -1 \quad \lambda_2 = 5$$

2) Find eigenvectors:

$$\lambda_1 = -1$$

$$\begin{bmatrix} 1-\lambda & 2 \\ 4 & 3-\lambda \end{bmatrix}$$

$$\begin{bmatrix} 1-(-1) & 2 \\ 4 & 3-(-1) \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 2 \\ 4 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 2 \\ 4 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$2v_1 + 2v_2 = 0$$

$$v_1 = -v_2 \quad \text{for } v_2 = 1$$

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = 5$$

$$\begin{bmatrix} 1-\lambda & 2 \\ 4 & 3-\lambda \end{bmatrix}$$

$$\begin{bmatrix} 1-5 & 2 \\ 4 & 3-5 \end{bmatrix}$$

$$\begin{bmatrix} -4 & 2 \\ 4 & -2 \end{bmatrix}$$

$$\begin{bmatrix} -4 & 2 \\ 4 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-4v_1 + 2v_2 = 0$$

$$2v_2 = 4v_1$$

$$v_2 = 2v_1$$

$$\begin{bmatrix} v_1 \\ 2v_1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \text{for } v_1 = 1$$

$$v_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

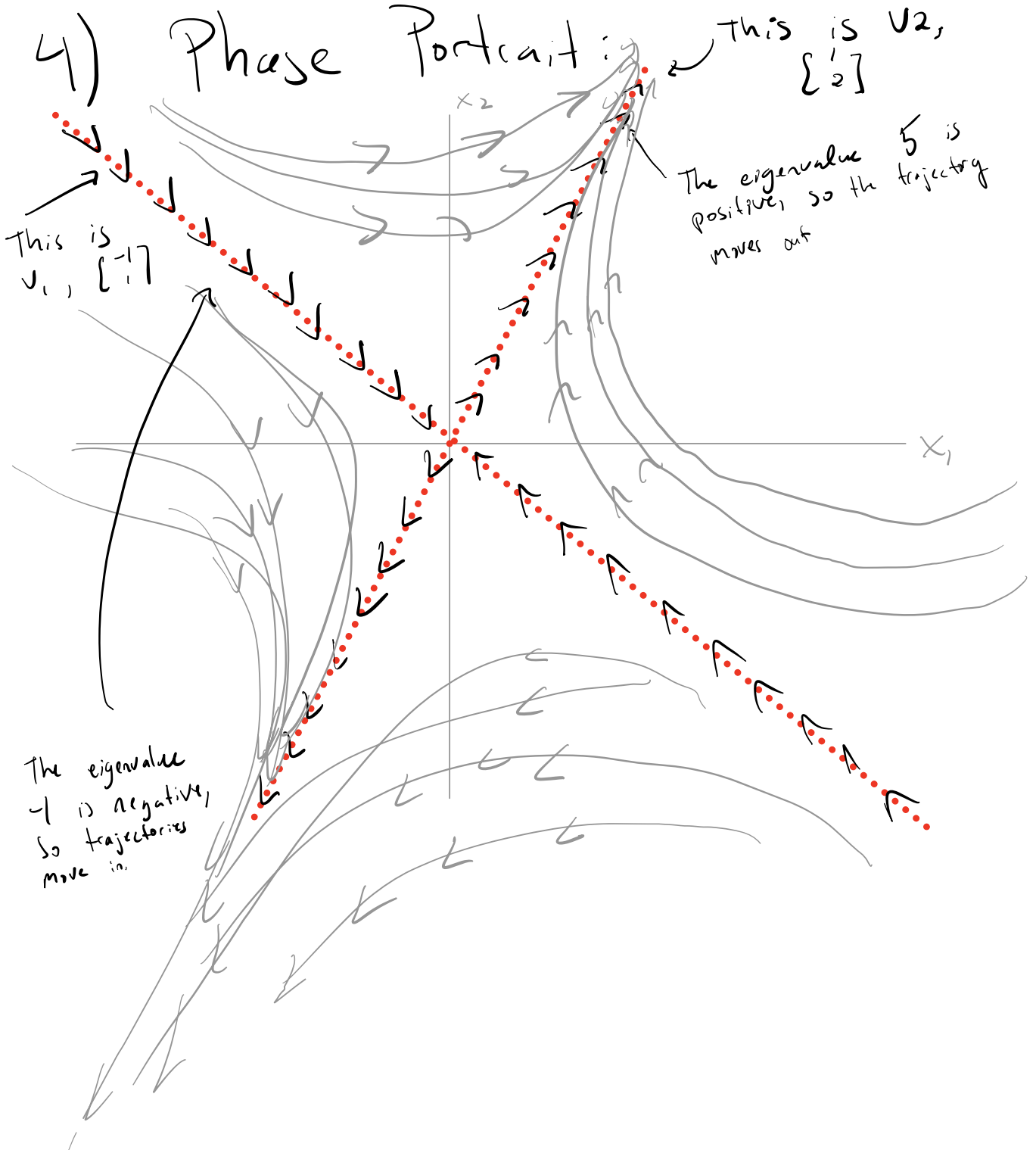
$$v_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

3) General Solution:

$$y(t) = C_1 e^{\lambda_1 t} v_1 + C_2 e^{\lambda_2 t} v_2$$

$$y(t) = C_1 e^{-t} \begin{bmatrix} -1 \\ 1 \end{bmatrix} + C_2 e^{5t} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

4) Phase Portrait:



This is v_2 ,
 $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

The eigenvalue 5 is positive, so the trajectory moves out

This is v_1 ,
 $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$

The eigenvalue -1 is negative, so trajectories move in.

2 -

The second problem will ask you to solve the Initial Value Problem for a 3×3 matrix. You will know the eigenvalues and eigenvectors from the problem statement. The notation of the problem may seem unusual, but don't worry! Only a few computations are required. If you are doing a lot of math, you are probably over thinking this problem.

Q2 will look something like:

Q2. Solve the IVP $\frac{dx}{dt} = Ax(t)$, $x(0) = \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}$,
where A is a constant matrix 3×3 satisfying:

$$i) A \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = 0$$

$$ii) (A - 3I) \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = 0,$$

iii) The vector $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ is an eigenvector of A with eigenvalue -1 .

Again, we are actually told our eigenvalues and eigenvectors.

First, remember that to obtain eigenvectors, we have

$$(A - \lambda I) \begin{bmatrix} v \end{bmatrix} = 0.$$

So, for

$$i) A \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = 0 \Rightarrow (A - 0I) \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = 0$$

$$\begin{aligned} \text{eigenvalue} &= 0 \\ \text{eigenvector} &= \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \end{aligned}$$

$$\text{ii) } (A - 3I) \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = 0$$

$$\begin{aligned} \text{eigenvalue} &= 3 \\ \text{eigenvector} &= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \end{aligned}$$

$$\text{iii) It is given to us that}$$
$$\begin{aligned} \text{eigenvalue} &= -1 \\ \text{eigenvector} &= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}. \end{aligned}$$

Here is how to solve:

General Solution:

$$\begin{aligned} x(t) &= C_1 e^{0t} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + C_3 e^{-t} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \\ &= C_1 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + C_3 e^{-t} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}. \end{aligned}$$

IVP.

$$\begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix} = C_1 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + C_3 e^{-t} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix} = C_1 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + C_2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + C_3 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$0 = C_1 + C_2$$

$$0 = 2C_1 + C_3$$

$$2 = C_3$$

$$\underline{C_3 = 2}$$

$$0 = 2C_1 + 2$$

$$C_1 = -1$$

$$0 = C_1 + C_2$$

$$0 = -1 + C_2$$

$$C_2 = 1$$

So, the solution to the
IVP is:

$$C_1 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + C_3 e^{-t} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$x(t) = - \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + e^{3t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 2e^{-t} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

3 - This question has 3 parts:

$$2y'' + \frac{1}{t-2} y' + 2y = e^t$$

1) What is the order?

2) Transform to a linear system of two first-order ODE's.

3) Find the maximum interval of existence of the solution of the ODE satisfying initial condition $y(0) = 1, y'(0) = 0$.

Solution

1) Order is 2.

(y'' is the highest order derivative of y)

2)

$$2y'' + \frac{1}{t-2}y' + 2y = e^t$$

First, let

$$u_1 = y$$

$$u_2 = y'$$

Then,

$$u_1' = y' = u_2$$

$$u_2' = y''$$

$$u_2' = y'' = -\frac{1}{t-2}y' - 2y + e^t$$

$$u_2' = -\frac{1}{t-2}u_2 - 2u_1 + e^t$$

$$u_1' = u_2$$

$$u_2' = -\frac{1}{t-2}u_2 - 2u_1 + e^t$$

3) Max interval:

$$y'' + \frac{1}{t-2} y' + 2y = e^t$$

a) Put in Standard Form
(This one already is)

b) Consider the function
coefficients:

$\frac{1}{t-2} \rightarrow$ continuous on $(-\infty, 2)$ and $(2, \infty)$

$2 \rightarrow$ continuous on $(-\infty, \infty)$

$e^t \rightarrow$ continuous on $(-\infty, \infty)$

IVP is $y(0) = 1, y'(0) = 0$

the maximum overlapping
interval containing \emptyset
is

$(-\infty, 2)$
